| L Number | Hits | Search Text | DB | Time stamp |
|---|---|---|---|---|
| - | 698 | manufacturing adj cell | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 629 | geometric adj description | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 10780 | tree adj structure | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 5183 | (tree adj structure) and database | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 4154 | cost adj function | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 6874 | weighted adj sum | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 292 | (cost adj function) with distance | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 50513 | degree adj2 freedom | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 171 | (degree adj2 freedom) with rotation with orientation | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 199 | traveling adj salesman adj problem | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 6323 | template and robot$ | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 49794 | link and joint | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 595 | (template and robot$) and (link and joint) | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 272 | sensor and ((template and robot$) and (link and joint)) | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 163 | (sensor and ((template and robot$) and (link and joint))) and coordinate and (movement motion) | USPAT; US-PGPUB | 2004/09/30 07:58 |
| - | 60 | (manufacturing adj cell) and workpiece | USPAT; US-PGPUB | 2004/09/30 07:59 |
| - | 288 | 703/1.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 1 | ((manufacturing adj cell) and workpiece) and geometric adj description | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 5 | (manufacturing adj cell) and (geometric adj description) | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 449 | ((tree adj structure) and database) and joint | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 136 | 703/8.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 95 | 703/7.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 12 | 4877940.URPN. | USPAT | 2004/09/30 08:00 |
| - | 16 | attracting adj pairs | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 247 | 703/6.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 5 | repelling adj pairs | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 6 | ("4912657" \| "5586052" \| "5771342" \| "5835693" \| "5980084" \| "6063126").PN. | USPAT | 2004/09/30 08:00 |
| - | 62 | (manufacturing adj cell) and optimization | USPAT; US-PGPUB | 2004/09/30 08:00 |
| - | 3 | ("5748847" \| "6031935" \| "6395478").PN. | USPAT | 2004/09/30 08:00 |
| - | 32 | ("3654615" \| "4495559" \| "4607339" \| "4615010" \| "4931944" \| "5077676" \| "5134685" \| "5136686" \| "5153923" \| "5159682" \| "5200908" \| "5218551" \| "5224056" \| "5225991" \| "5235521" \| "5237514" \| "5308798" \| "5326659" \| "5333032" \| "5339253" \| "5349536" \| "5359535" \| "5363313" \| "5388055" \| "5402357" \| "5416718" \| "5432447" \| "5557533" \| "5563783" \| "5568636" \| "5619419" \| "5636125").PN. | USPAT | 2004/09/30 08:00 |
| - | 34 | value with joint with limit with within | USPAT; US-PGPUB | 2004/09/30 08:00 |

| | | | | |
|---|---|---|---|---|
| – | 2 | kinematic adj tree | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 33 | ((cost adj function) with distance) and (weighted adj sum) | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 13 | igrip | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 1 | ("5043929").PN. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 20 | robcad | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 3 | ((degree adj2 freedom) with rotation with orientation) and (pair near3 point) | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 13 | ("3321072" \| "3909600" \| "3920972" \| "4381608" \| "4591771" \| "4705451" \| "4811235" \| "4920500" \| "5053975" \| "5053976" \| "5129044" \| "5129045" \| "5471395").PN. | USPAT | 2004/09/30 08:00 |
| – | 11 | 5604677.URPN. | USPAT | 2004/09/30 08:00 |
| – | 9 | congruent with (pair near3 point) | USPAT | 2004/09/30 08:00 |
| – | 24 | 4891762.URPN. | USPAT | 2004/09/30 08:00 |
| – | 22 | (traveling adj salesman adj problem) and 3d | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 1 | ("6507771").PN. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 14 | ("4028533" \| "5233604" \| "5561790" \| "5675741" \| "5946083" \| "5991300" \| "6154139" \| "6195020" \| "6208247" \| "6311129" \| "6330493" \| "6341246" \| "6374155" \| "6408226").PN. | USPAT | 2004/09/30 08:00 |
| – | 4 | (("4851748") or ("4954762") or ("5357439") or ("6004016")).PN. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 42 | ((sensor and ((template and robot$) and (link and joint))) and coordinate and (movement motion)) and tree | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 138 | 700/56.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 74 | 700/96.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |
| – | 43 | 700/251.ccor. | USPAT; US-PGPUB | 2004/09/30 08:00 |